





# YUCO micro-AUVs

New solution to monitor coastal waters.

EOOS conference March 2022

# Coastal monitoring... challenging environment



## Fixed measurements

- Cabled / autonomous observatory
- Stationary buoys



Long-term

- Installation/Maintenance costs
- No spatialisation

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## From surface vessel

- Hand-Held and towed instruments
- USVs
- ROVs



### Short-term

- Human action dependent
- Mainly surface
- Wave dependent



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## Autonomous platforms

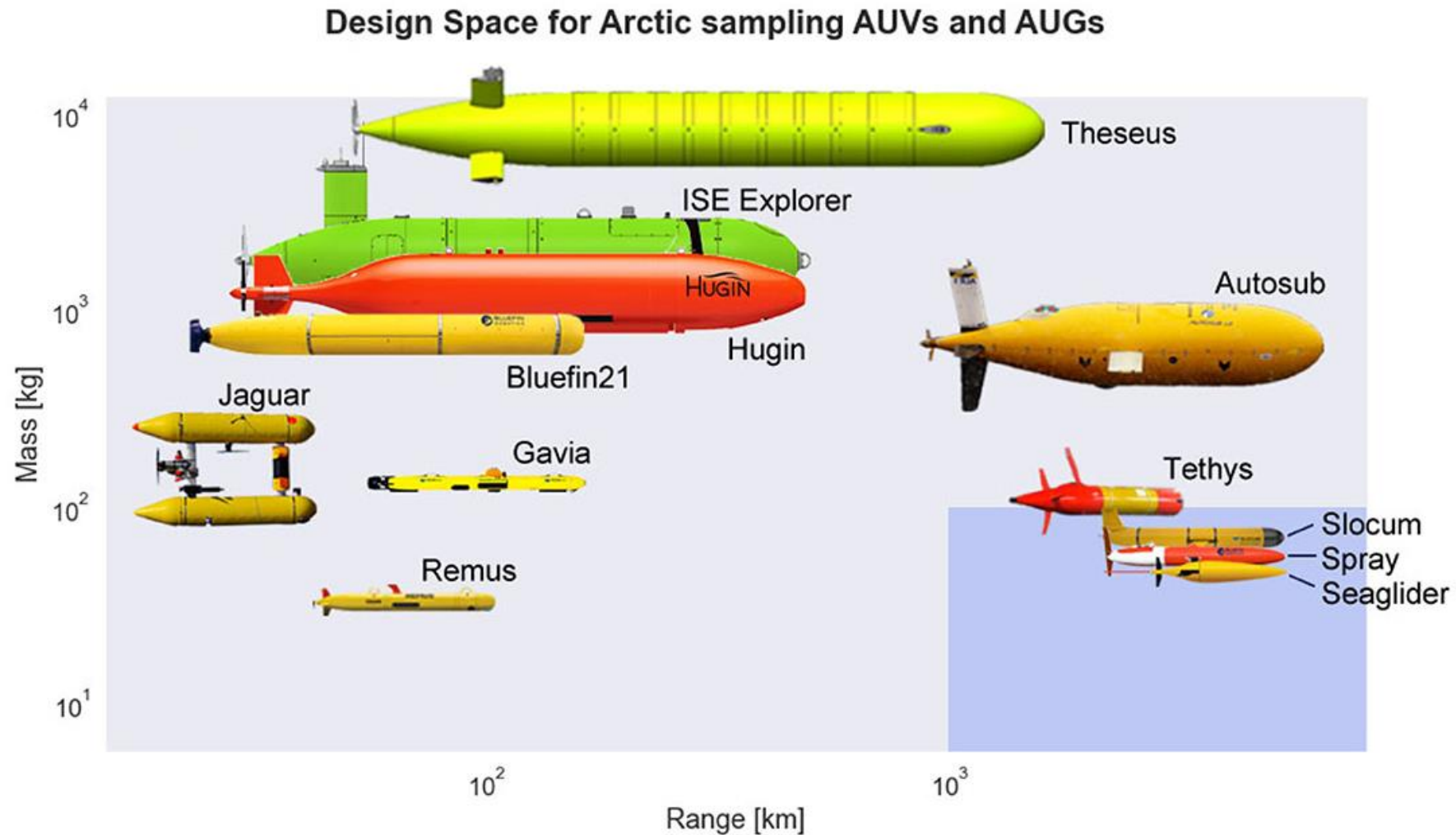
- AUVs
- Gliders and floats



### Short & Long-term

- Deployment capabilities
- Current dependant

# Coastal monitoring... challenging environment



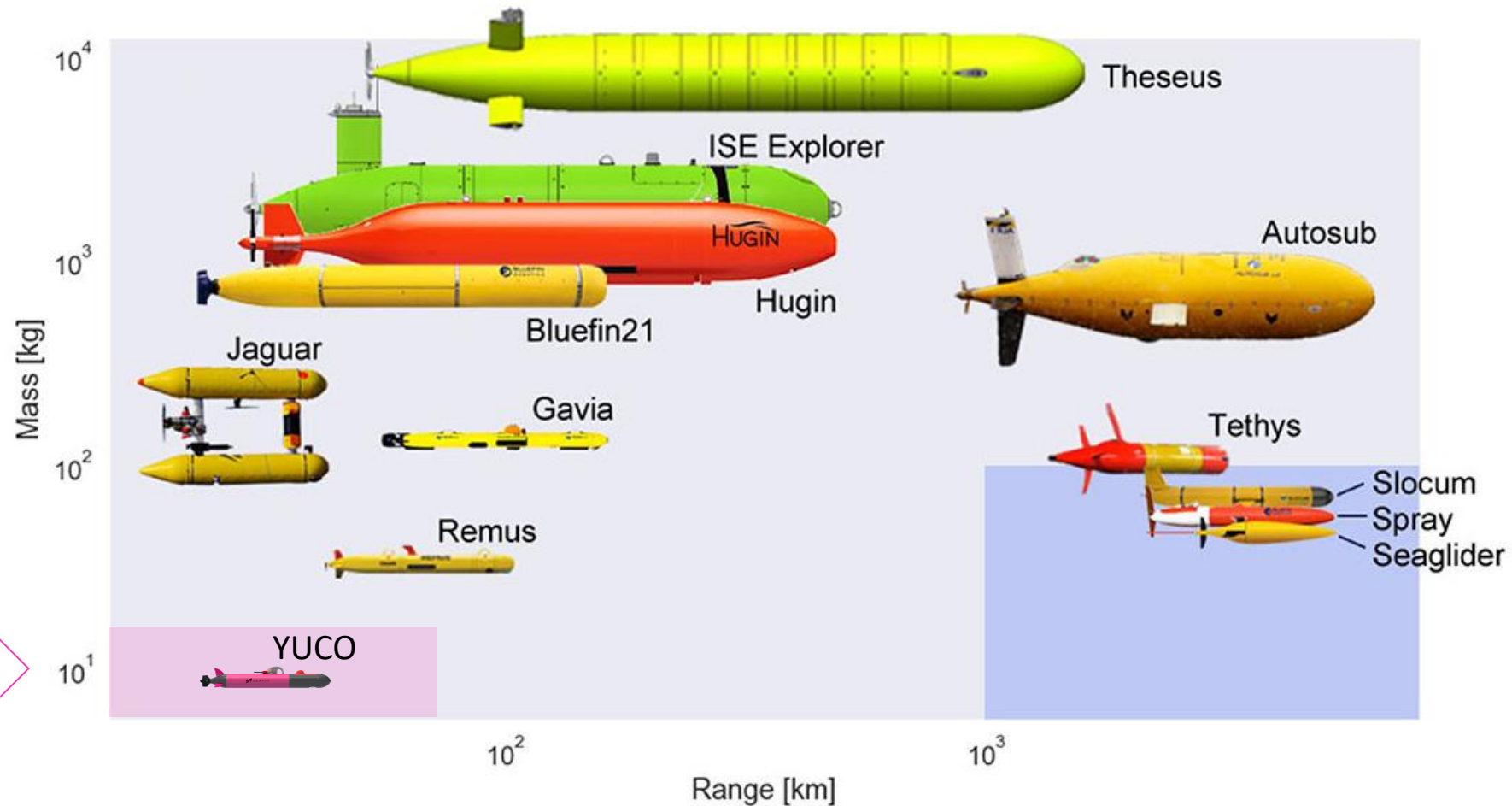
Source : Improving Resource Management for Unattended Observation of the Marginal Ice Zone Using Autonomous Underwater Gliders

[Zachary Duguid](#) and [Richard Camilli](#)

# Coastal monitoring... challenging environment



Design Space for Arctic sampling AUVs and AUGs



Source : Improving Resource Management for Unattended Observation of the Marginal Ice Zone Using Autonomous Underwater Gliders

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The YUCO micro-AUV aim is to :

- fill the gap in coastal waters monitoring
- measure in hard to access areas
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Well... in a way... to use an AUV in coastal waters as an AUV is meant to be used.

# YUCO-Carrier – Main features



- ▶ < 10kg in air
  - ▶ 300m depth rated
  - ▶ Up to 6knots
  - ▶ Up to 10 hours Li-ion (~3h with NiMH version)
  - ▶ Up to 50cm / 2km in payload section
  - ▶ INX © Naigation accuracy
    - ▶ 2% or better with DVL
    - ▶ 2 to 10% without DVL
- NO NEED OF EXTERNAL POSITIONING SYSTEM**



# YUCO micro-AUV range



## YUCO-SCAN



## YUCO-PAM



## YUCO-CTD



## YUCO-PHYSICO



# YUCO micro-AUV range



## YUCO-SCAN



## YUCO-PAM



## YUCO-CTD



## YUCO-PHYSICO



... Hopefully more to come in 2022!



The YUCO micro-AUV is able to :

- Be programmed by non AUV specialist
- Be deployed by any operator – even if it is the first time they have a YUCO micro-AUV in their hands



# Mission edit - Layout



Menu and  
toolbar

Seaplan

Mission AUV Dashboard Data Debrief

YUCO AUV

Step properties

Waypoint #4  
Latitude (deg) 50.762684  
Longitude (deg) -0.989462  
Speed (m/s) 2.0  
Max duration (s) 3447  
Depth (m) 5.0 below surface  
Vertical speed (m/s) 0.34  
Tolerance radius (m) 20  
Path shape sawtooth  
Height (m) 3.0  
Upspeed (m/s) 0.2  
Downdepth (m/s) 0.2

Actions

↓ Screw  
↑ Screw  
Wait GPS

+ Add

Depth view

Activation depth (m) 0.3  
Min altitude (m) 2  
Max depth (m) 300  
Speed (m/s) 2 m/s 2 m/s 3 m/s 2 m/s

Mission summary

Mission name Bathysedi\_202106  
Mission duration 3h 42min  
Mission length 12.3 km  
Required power : 38%  
Upload to AUV

Step  
properties

Mission  
summary

CONFIDENTIAL



Seaplan Demo

Home

Mission

AUV Dashboard

DEMONSTRATION VERSION: DO NOT DISTRIBUTE

YUCO AUV

New mission

Open mission

Load from AUV

Save mission

Save mission as

Add Layer

Change coord syst.

Hand

Pointer

Line

Circle

Rectangle

Eraser

Undo

Redo

N 53.19635° W 009.13377°

0m  
5m  
10m  
15m  
20m  
25m  
30m

Screw Properties

Speed (m/s)

2.0

Radius (m)

15

Rotation direction

clockwise

End condition

reach target dept

Depth pattern

From surface

Depth from surface

Depth (m)

30.0

Vertical speed (m/s)

0.10

Payload frame

Hex mode 0 / 120

Mode

Mission file

SeaplanCampaign

Mission name

NewMission

2h 44m

20.35km

79%

Settings

Upload to AUV





Seaplan Demo

Mission AUV Dashboard DEMONSTRATION VERSION: DO NOT DISTRIBUTE YUCO AUV

New mission  
Open mission  
Load from AUV  
Save mission  
Save mission as  
Add Layer  
Change coord syst.

Map view showing a mission path (red line) and waypoints (red pins) over a coastal area. The path starts at a point labeled "Middle West" and proceeds through several waypoints, ending at a point labeled "Barna". The map includes labels for "Barna Road", "Coisméig Mór", and "Barna". A coordinate box shows "N 53.24997° W 009.09983°".

Segment Properties

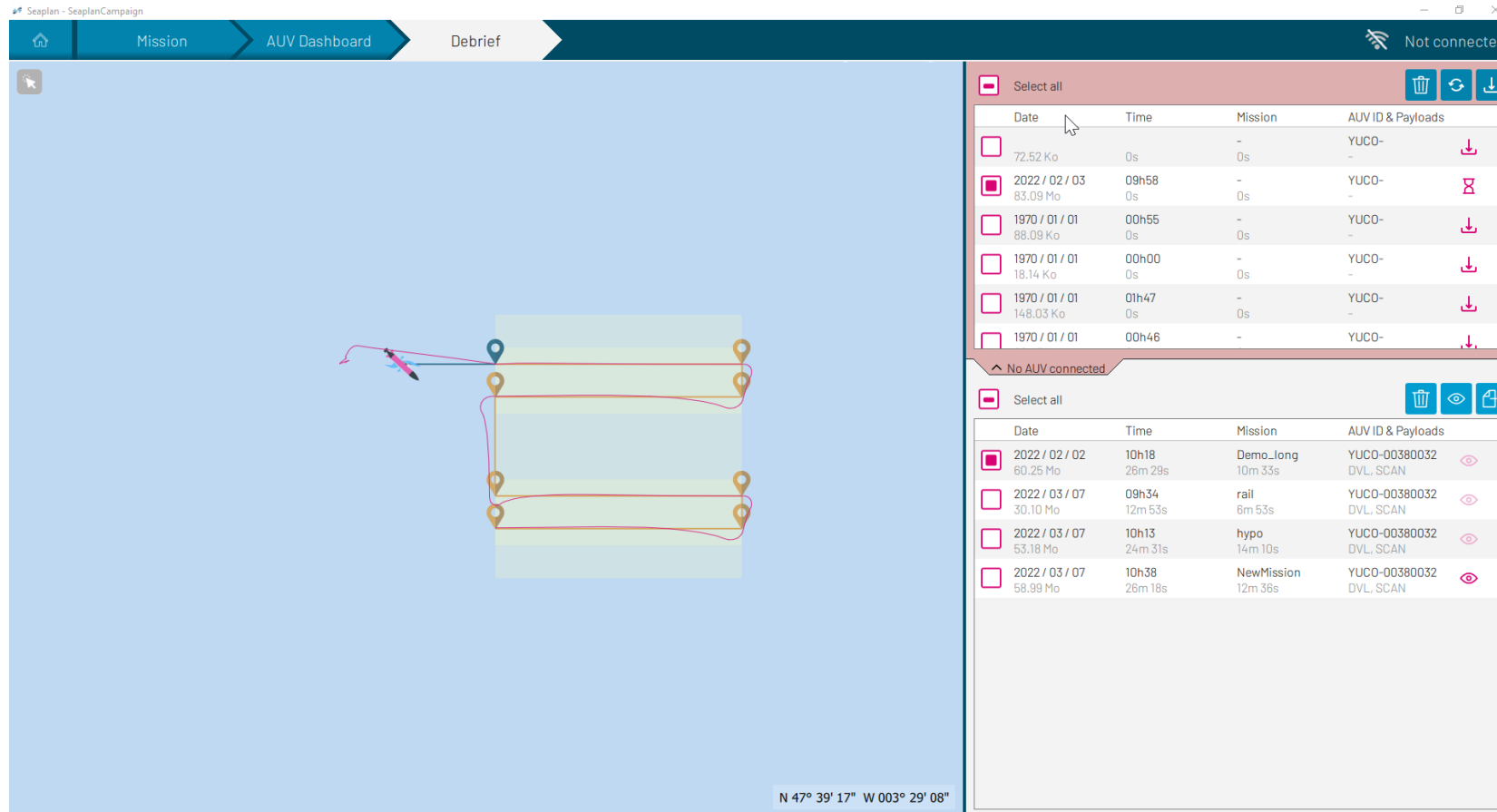
Bearing (deg) 280  
Speed (m/s) 2.0  
Duration (s) 1700  
Depth pattern From seabed  
Distance from seabed  
Distance (m) 5.0  
Vertical speed (m/s) 0.34

Payload frame Hex mode 0 / 120 Mode

Mission file SeaplanCampaign  
Mission name NewMission  
2h 37m 18.93km 58%  
Settings Upload to AUV

0m  
5m  
10m  
15m  
20m  
25m  
30m

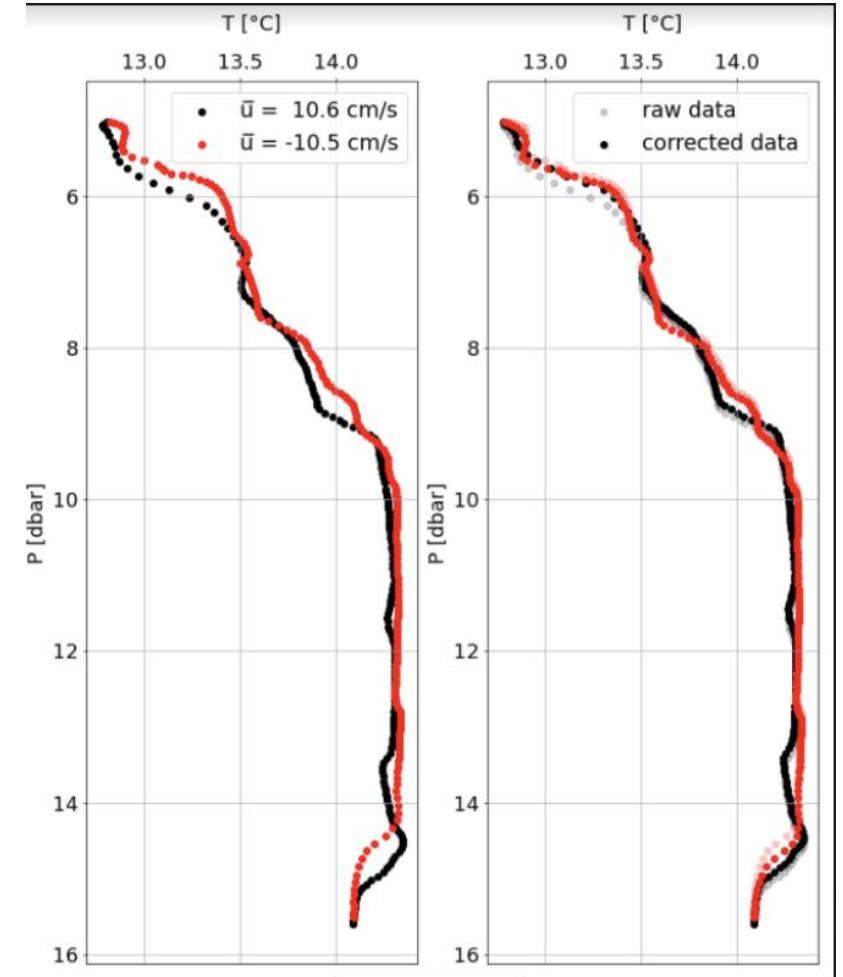
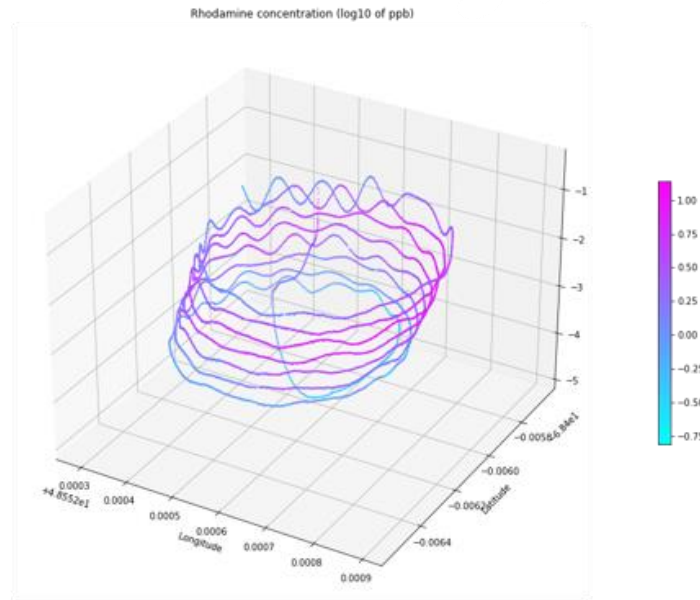
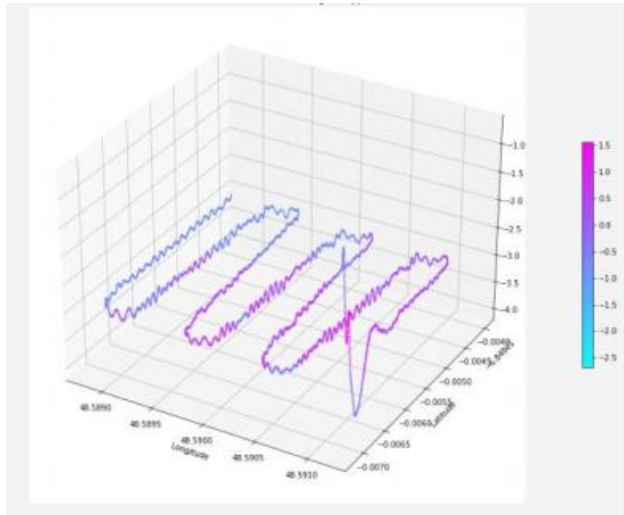
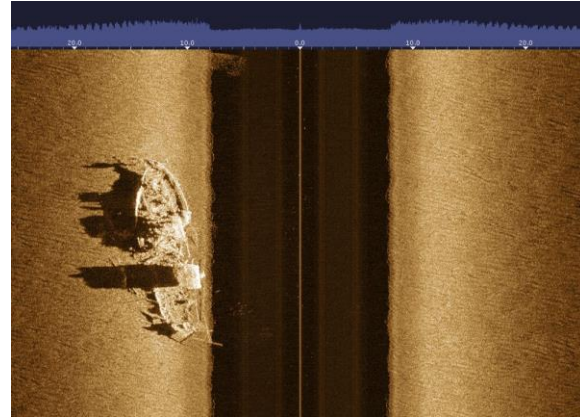
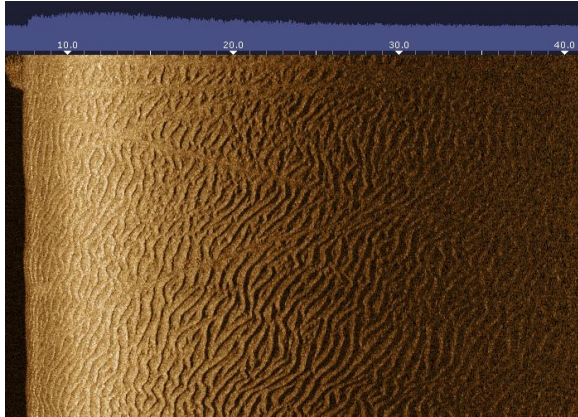
# Mission debriefs



- Sensor synch with nav in csv
- All nav and internal files at 20Hz



# Some data...





- ▶ increased periodicity, spatialization and duration of in-situ measurements with reduced costs,
- ▶ measurements in hard to access area,
- ▶ ability to deploy and recover from any type of vessel or even from the shore, and by non-trained operators,
- ▶ increased quality and variety of measurements.

# Some partners / customers...



Thanks



Thanks a lot 😊

... not sure there is time for  
questions so



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[www.seaber.fr](http://www.seaber.fr)